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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
09/623,440	09/05/2000	Tsuyoshi Takagi	450108-02280	3925

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FROMMER LAWRENCE & HAUG  
745 FIFTH AVENUE- 10TH FL.  
NEW YORK, NY 10151

EXAMINER
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WOZNIAK, JAMES S

ART UNIT	PAPER NUMBER
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2655

DATE MAILED: 06/22/2004

Please find below and/or attached an Office communication concerning this application or proceeding.

**Office Action Summary**

Application No.

09/623,440

Applicant(s)

TAKAGI ET AL.

Examiner

James S. Wozniak

Art Unit

2655

-- The MAILING DATE of this communication appears on the cover sheet with the correspondence address --

**Period for Reply**

A SHORTENED STATUTORY PERIOD FOR REPLY IS SET TO EXPIRE 3 MONTH(S) FROM THE MAILING DATE OF THIS COMMUNICATION.

- Extensions of time may be available under the provisions of 37 CFR 1.136(a). In no event, however, may a reply be timely filed after SIX (6) MONTHS from the mailing date of this communication.
- If the period for reply specified above is less than thirty (30) days, a reply within the statutory minimum of thirty (30) days will be considered timely.
- If NO period for reply is specified above, the maximum statutory period will apply and will expire SIX (6) MONTHS from the mailing date of this communication.
- Failure to reply within the set or extended period for reply will, by statute, cause the application to become ABANDONED (35 U.S.C. § 133). Any reply received by the Office later than three months after the mailing date of this communication, even if timely filed, may reduce any earned patent term adjustment. See 37 CFR 1.704(b).

**Status**

- 1) ☒ Responsive to communication(s) filed on 5/14/04.
- 2a) ☒ This action is **FINAL**. 2b) ☐ This action is non-final.
- 3) ☐ Since this application is in condition for allowance except for formal matters, prosecution as to the merits is closed in accordance with the practice under *Ex parte Quayle*, 1935 C.D. 11, 453 O.G. 213.

**Disposition of Claims**

- 4) ☒ Claim(s) 1-8 and 10-12 is/are pending in the application.
- 4a) Of the above claim(s) \_\_\_\_\_ is/are withdrawn from consideration.
- 5) ☐ Claim(s) \_\_\_\_\_ is/are allowed.
- 6) ☒ Claim(s) 1-8 and 10-12 is/are rejected.
- 7) ☐ Claim(s) \_\_\_\_\_ is/are objected to.
- 8) ☐ Claim(s) \_\_\_\_\_ are subject to restriction and/or election requirement.

**Application Papers**

- 9) ☐ The specification is objected to by the Examiner.
- 10) ☒ The drawing(s) filed on 09/05/2000 is/are: a) ☒ accepted or b) ☐ objected to by the Examiner.
- Applicant may not request that any objection to the drawing(s) be held in abeyance. See 37 CFR 1.85(a).
- Replacement drawing sheet(s) including the correction is required if the drawing(s) is objected to. See 37 CFR 1.121(d).
- 11) ☐ The oath or declaration is objected to by the Examiner. Note the attached Office Action or form PTO-152.

**Priority under 35 U.S.C. § 119**

- 12) ☒ Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f).
- a) ☒ All b) ☐ Some \* c) ☐ None of:
1. ☒ Certified copies of the priority documents have been received.
  2. ☐ Certified copies of the priority documents have been received in Application No. \_\_\_\_\_.
  3. ☐ Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)).

\* See the attached detailed Office action for a list of the certified copies not received.

**Attachment(s)**

- |  |   |
|--|---|
| 1) <input type="checkbox"/> Notice of References Cited (PTO-892)   | 4) <input type="checkbox"/> Interview Summary (PTO-413)<br>Paper No(s)/Mail Date. _____ |
| 2) <input type="checkbox"/> Notice of Draftsperson's Patent Drawing Review (PTO-948)                                   | 5) <input type="checkbox"/> Notice of Informal Patent Application (PTO-152)             |
| 3) <input type="checkbox"/> Information Disclosure Statement(s) (PTO-1449 or PTO/SB/08)<br>Paper No(s)/Mail Date _____ | 6) <input type="checkbox"/> Other: _____  |

**Detailed Action**

***Response to Amendment***

1. In response to the office action from 2/13/04, the applicant has submitted an amendment, filed 5/14/04, canceling Claim 9 and amending Claims 1, 11, and 12 to include the subject matter of cancelled Claim 9, while arguing to traverse the art rejection based on the limitation regarding the transitioning of behavior sets based on probability (*Amendment, Page 7*). Applicant's arguments have been fully considered, however the previous art rejections are maintained with respect to the amended claims and without the addition of any new prior art:

***Response to Arguments***

2. The applicant's arguments have been fully considered but they are not persuasive for the following reasons:
- With respect to **Claims 1, 11, and 12**, the applicant argues that Lund et al (*"Adaptive LEGO Robots"*) does not teach "a behavioral model that is a probability automaton prescribed by a state corresponding to a behavior and a transition probability of the state" (*Amendment, Pages 6-7*), however in this regard, Lund specifically teaches the use of probability in selecting a behavior set that changes with time and is based upon a current behavior state (Behavior Set Selector, Page 1021), which is a functional equivalent of the probability

automation of the present invention. Thus, Lund et al sufficiently teaches a behavioral model as a probability automaton.

- In response to applicant's argument that the references fail to show certain features of applicant's invention, it is noted that the features upon which applicant relies (*i.e., probability equations used by the probability automaton to determine the transitions between behavioral models, Amendment, Page 7*) are not recited in the rejected claim(s). Although the claims are interpreted in light of the specification, limitations from the specification are not read into the claims. See *In re Van Geuns*, 988 F.2d 1181, 26 USPQ2d 1057 (Fed. Cir. 1993).
- The rejection of **Claim 7** is argued as being dependent upon Claim 1 which contains the probability automation limitation noted above (*Amendment, Page 7*), thus since Lund teaches this feature, the rejection of Claim 7 and the other dependent claims (2-6, 8, and 10) is maintained.
- The previous objection to the drawings noted on the PTOL-326 form was in error and has been withdrawn.

### ***Claim Rejections - 35 USC § 103***

3. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:

(a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negated by the manner in which the invention was made.

4. **Claims 1-6, 8, and 10-12** are rejected under 35 U.S.C. 103(a) as being unpatentable over Kamiya et al (*U.S. Patent: 6,175,772*) in view of Lund et al ("*Adaptive LEGO Robots. A Robot-Human View on Robotics*").

With respect to **Claim 1**, Kamiya discloses:

A mechanical device, characterized by comprising:

Drive means for performing a behavior (*drive means and display, Col. 10, Lines 44-62*);

Stimulus detection means for detecting a stimulus (*Col. 4, Lines 6-14*);

Storage means for storing a behavioral model prescribing a behavior (*storage means for storing user intentions related with emotional models in a model for deciding robot behavior, Col. 7, Lines 33-46*);

Control means for controlling said drive means based on the behavioral model stored in said storage means (*behavior decision means for controlling robot functions, Col. 8, Lines 51-58*);

Changing means for changing the behavioral model based on a predetermined stimulus detected by said stimulus detection means (*learning and altering behavior based upon user interaction, Col. 7, Lines 3-25*).

Kamiya does not teach the behavioral model as a probability automaton prescribed by a state corresponding to a behavior and transition probability of the state, however Lund recites:

Behavioral model is a probability automaton prescribed by a state corresponding to a behavior and transition probability of the state (*robot behavior determined by an internal state contained within a behavior set, Page 1021, Behavior Set and Behavior Engine, Fig. 7, and Behavior Set Selector, Page 1021*); and

Changing means changes transition probability in the probability automaton based on the detected stimulus (*creation of emergent behaviors based on external stimulus, Page 1021, Behavior Set, Paragraph 2, and Behavior Set Selector, Page 1021*).

Kamiya and Lund are analogous art because they are from a similar field of endeavor in user interaction with an entertainment robot. Thus, it would have been obvious to a person of ordinary skill in the art, at the time of invention, to combine the use of probabilistic internal states in determining robot behavior as taught by Lund with the interactive robot capable of detecting user inputs as stimulus to produce, learn, or alter a behavior as taught by Kamiya to allow for more adaptive robot behavior, thus allowing for increased realism in robot interaction. Therefore, it would have been obvious to combine Lund with Kamiya for the benefit of obtaining an interactive, life-like robot capable of quickly adapting to environment and user input, to obtain the invention as specified in Claim 1.

With respect to **Claim 2**, Kamiya further recites:

Stimulus is provided by a user (*sensing means detecting stimulus from a user, Col. 4, Lines 6-14*).

With respect to **Claim 3**, Kamiya additionally discloses:

Stimulus detection means comprising a pressure sensor detecting pressure provided by the user as stimulus (*Col. 4, Line 8, Fig. 3, Element 4*); and

Changing means for changing the behavioral model based on a predetermined stimulus detected by the stimulus detection means (*evolving robot behavior based upon a tactile user input, Col. 4, Lines 47-64*).

With respect to **Claim 4**, Kamiya further recites:

Stimulus detection means comprising a pressure sensor detecting pressure provided by the user as stimulus (*Col. 4, Line 8, Fig. 3, Element 4*); and

Changing means changes the behavioral model based on a size and length of pressure detected by a pressure sensor (*pressure amount detection, Col. 5, Lines 54-58, tactile duration detection, Col. 5, Lines 38-41. and the generation of emotions for changing robot behavior according to tactile data, Col. 6, Lines 6-10*).

With respect to **Claim 5**, Kamiya additionally discloses:

Stimulus detection means comprises a microphone collecting voice provided by the user as the stimulus (*Col. 4, Lines 36-38, and Fig. 3, Element 8*); and

Changing means changes the behavioral model based on the voice collected by the microphone (*evolving robot behavior based upon an audio user input from a microphone, Col. 4, Lines 47-64*).

With respect to **Claim 6**, Kamiya further recites:

Stimulus detection means further comprises a speech recognition means (*voice detection unit that analyzes a voice input from the microphone using speech recognition means, Col. 5, Lines 59-65*); and

Changing means changes the behavioral model based on a speech recognition result of the voice by the speech recognition means (*evolving robot behavior based upon a voice input from a microphone, Col. 4, Lines 47-64*).

With respect to **Claim 8**, Kamiya further recites:

Stimulus detection means further comprises a prosody information detection means detecting prosody information about the voice (*detecting the tone of a voice input to determine user emotion, Col. 4, Lines 10-12*); and

Changing means changes the behavioral model according to the prosody information detected by the prosody information detection means (*evolving robot behavior based upon user emotion data contained in a voice input from a microphone, Col. 4, Lines 47-64*).

With respect to **Claim 10**, Kamiya teaches the interactive robot capable of detecting user voice and tactile inputs as stimulus to produce, learn, or alter a behavior as applied to Claim 1. Kamiya does not teach a time lapse as a stimulus for returning to an original state of operation, however Lund suggests:

Changing means restores the behavioral model to an original state depending on a time lapse after changing the behavioral model (necessity for sleep behavior returned to from an awakened state after a duration of time within a 24 hour cycle, Page 1022, State Variables, Paragraph 2).

Kamiya and Lund are analogous art because they are from a similar field of endeavor in user interaction with an entertainment robot. Thus, it would have been obvious to a person of ordinary skill in the art, at the time of invention, to combine the time duration in prescribing a robot behavior as taught by Lund with the interactive robot capable of detecting user voice and tactile inputs as stimulus to produce, learn, or alter a behavior as taught by Kamiya to allow for increased robot realism through the performance of various behaviors at specific durations in time. Therefore, it would have been obvious to combine Lund with Kamiya for the benefit of



obtaining an interactive, life-like robot capable of performing specific behaviors at designated times, to obtain the invention as specified in Claim 10.

With respect to **Claim 11**, Kamiya discloses:

Control step and for controlling drive means to perform a behavior based on a behavioral model prescribing a behavior (*behavior decision means for controlling robot functions, Col. 8, Lines 51-58*);

Stimulus detecting step of detecting a stimulus (*Col. 4, Lines 6-14*); and

A changing step of changing the behavioral model based on a detected predetermined stimulus (*learning and altering behavior based upon user interaction, Col. 7, Lines 3-25*).

Kamiya does not teach the behavioral model as a probability automaton prescribed by a state corresponding to a behavior and transition probability of the state, however Lund recites:

Behavioral model is a probability automaton prescribed by a state corresponding to a behavior and transition probability of the state (*robot behavior determined by an internal state contained within a behavior set, Page 1021, Behavior Set and Behavior Engine, Fig. 7, and Behavior Set Selector, Page 1021*); and

Changing means changes transition probability in the probability automaton based on the detected stimulus (*creation of emergent behaviors based on external stimulus, Page 1021, Behavior Set, Paragraph 2, and Behavior Set Selector, Page 1021*).

Kamiya and Lund are analogous art because they are from a similar field of endeavor in user interaction with an entertainment robot. Thus, it would have been obvious to a person of ordinary skill in the art, at the time of invention, to combine the use of probabilistic internal states in determining robot behavior as taught by Lund with the interactive robot control method

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for detecting user inputs as stimulus to produce, learn, or alter a behavior as taught by Kamiya to allow for more adaptive robot behavior, thus allowing for increased realism in robot interaction. Therefore, it would have been obvious to combine Lund with Kamiya for the benefit of obtaining a robot control method for quickly adapting robot behavior to environment and user input, to obtain the invention as specified in Claim 11.

With respect to **Claim 12**, Kamiya in view of Lund teaches the interactive robot capable of detecting user voice and tactile inputs as stimulus to produce, learn, or alter a behavior as applied to Claim 11 and program command that controls robot operation (*Col. 2, Line 17*).

Neither Kamiya nor Lund specifically teaches the use of a recording medium containing such a program, however, it would have been obvious to one of ordinary skill in the art at the time of invention, to implement the robot operating program on a CD-ROM or other such recording medium for the purpose of pre-programming a robot or allowing a robot to follow a pre-set sequence of behavior by inserting a recording medium containing a program into the robot device.

5. **Claim 7** is rejected under 35 U.S.C. 103(a) as being unpatentable over Kamiya et al in view of Lund et al and further in view of Fujita et al (*U.S. Patent: 5,966,690*).

With respect to **Claim 7**, Kamiya in view of Lund teaches the interactive robot capable of recognizing user voice input as stimulus to produce, learn, or alter a behavior as applied to Claim

6. Kamiya in view of Lund does not teach the use of a dictionary in speech recognition of a user input, however Fujita discloses:

Speech recognition means comprises a dictionary storing a word to be voice-recognized corresponding to a method for changing the behavioral model, and outputting any of words stored in the dictionary as the speech recognition result (*word dictionary, containing words related to robot commands, used in speech recognition, Col. 20, Lines 12-40*);

Kamiya, Lund, and Fujita are analogous art because they are from a similar field of endeavor in user interaction with a robot through speech commands. Thus, it would have been obvious to a person of ordinary skill in the art, at the time of invention, to combine the use of a dictionary in speech recognition as taught by Fujita with the interactive robot capable of recognizing user voice input as stimulus to produce, learn, or alter a behavior as taught by Kamiya in view of Lund to provide a means, well known to one of ordinary skill in the art, at the time of invention, of storing recognized speech commands taught by Kamiya in a dictionary for more efficient speech recognition in robot interaction. Therefore, it would have been obvious to combine Fujita with Kamiya in view of Lund for the benefit of obtaining an interactive and configurable robot capable of efficiently recognizing a speech input through the use of a command word dictionary and utilizing this recognition output in combination with changing means to alter a robot behavior, to obtain the invention as specified in Claim 7.

### ***Conclusion***

6. Applicant's amendment necessitated the new ground(s) of rejection presented in this Office action. Accordingly, **THIS ACTION IS MADE FINAL**. See MPEP § 706.07(a). Applicant is reminded of the extension of time policy as set forth in 37 CFR 1.136(a).

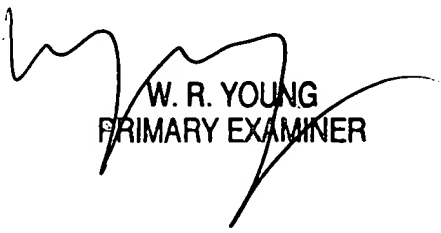
A shortened statutory period for reply to this final action is set to expire THREE MONTHS from the mailing date of this action. In the event a first reply is filed within TWO MONTHS of the mailing date of this final action and the advisory action is not mailed until after the end of the THREE-MONTH shortened statutory period, then the shortened statutory period will expire on the date the advisory action is mailed, and any extension fee pursuant to 37 CFR 1.136(a) will be calculated from the mailing date of the advisory action. In no event, however, will the statutory period for reply expire later than SIX MONTHS from the date of this final action.

7. Any inquiry concerning this communication or earlier communications from the examiner should be directed to James S. Wozniak whose telephone number is (703) 305-8669 and email is James.Wozniak@uspto.gov. The examiner can normally be reached on Mondays-Fridays, 8:30-4:30.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Talivaldis Ivars Smits can be reached at (703) 306-3011. The fax/phone number for the Technology Center 2600 where this application is assigned is (703) 872-9306.

Any inquiry of a general nature or relating to the status of this application or proceeding should be directed to the technology center receptionist whose telephone number is (703) 306-0377.

James S. Wozniak  
6/18/2004

  
W. R. YOUNG  
PRIMARY EXAMINER